

## AN INTRODUCTION TO TIME-SHIFT EQUATIONS

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ABSTRACT. Dilation Equations play an important role in Wavelet Multiresolution Approximation. A dilation equation is a difference equation for fixed scale summing over all time-shifts. In this note we introduce a class of equations called Time-Shift Equations. A time-shift equation is a difference equation for fixed time-shift summing over all scales. Analysis leading to derivation of these equations will occupy the rest of the note.

### 1. INTRODUCTION

This note is a brief introduction to a class of equations — called Time-Shift Equations (TiEq) — which is an analog of the class of Dilation Equations (DiEq).

Dilation Equations “live” in Wavelet Multiresolution Approximation (MRA), see for instance the paper of Strang [12] and the book of Keinert [4, Chapter 1]. The basic DiEq, also called “refinement equation”, is a two-scale difference equation, of the form

$$(1.1) \quad \phi(\cdot) = \sum_{n \in \mathbb{Z}} c_n \phi(2(\cdot) - n) = \sum_{n \in \mathbb{Z}} c_n DT^n \phi(\cdot),$$

where  $\phi(\cdot) \in \mathcal{L}^2(\mathbb{R})$  called scaling function — generating a MRA  $\mathcal{L}^2(\mathbb{R})$ -subspaces  $\{\mathcal{V}_m\}_{m \in \mathbb{Z}}$  — is normalized so that [12]

$$(1.2) \quad \int_{-\infty}^{\infty} \phi(t) dt = 1 \quad \implies \quad \sum_{n \in \mathbb{Z}} c_n = 2.$$

Here and in what follows  $D$  and  $T$  are, respectively, dyadic-scale and unit-time-shift  $\mathcal{L}^2(\mathbb{R})$ -operators defined by

$$(1.3) \quad Df(\cdot) = \sqrt{2}f(2(\cdot)) \quad \text{and} \quad Tf(\cdot) := f((\cdot) - 1).$$

The basic Time-Shift Equation to be derived is the difference equation of the form (for some  $\varphi(\cdot) \in \mathcal{L}^2(\mathbb{R})$ )

$$(1.4) \quad \varphi(\cdot) = \sum_{m \in \mathbb{Z}} \beta_m \sqrt{2}^m \varphi(2^m(\cdot) - 1) = \sum_{m \in \mathbb{Z}} \beta_m D^m T \varphi(\cdot).$$

We note that  $m$  always stands for scale level and  $2^m$  is scale while  $n$  is time-shift. Thus the right hand side of equation (1.1) is for scale level  $m = 1$  or for scale  $2^1$ , over all time-shifts, while that of equation (1.4) is at time-shift 1 over all scale levels.

Background and steps leading to TiEq will be presented in Section 2. The Connection between TiEq and DiEq is shown in Section 3.

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## 2. WHY TIME-SHIFT EQUATIONS?

Let  $\psi(\cdot) \in \mathcal{L}^2(\mathbb{R})$  be a wavelet and let  $\psi_{m,n}(\cdot)$ ,  $(m, n) \in \mathbb{Z}^2$ , be the wavelet functions generated from  $\psi(\cdot)$  by time-shiftings followed by dyadic-scalings, that is,

$$(2.1) \quad \psi_{m,n}(\cdot) := \sqrt{2^m} \psi(2^m(\cdot) - n) = D^m T^n \psi(\cdot) = D^m \psi((\cdot) - n), \quad (m, n) \in \mathbb{Z}^2.$$

Then, by definition,  $\{\psi_{m,n}(\cdot)\}$  is a double-indexed  $\mathcal{L}^2(\mathbb{R})$ -orthonormal basis (o.n.b.) [5, 9]. As a consequence the “scale detail subspaces”  $\mathcal{W}_m(\psi)$  constructed from  $\psi_{m,n}(\cdot)$  as

$$(2.2) \quad \mathcal{W}_m(\psi) := \bigvee_{n \in \mathbb{Z}} D^m \psi((\cdot) - n), \quad m \in \mathbb{Z},$$

constitute an  $\mathcal{L}^2(\mathbb{R})$ -orthogonal subspaces basis (o.s.b.) [7]. Therefore the space  $\mathcal{L}^2(\mathbb{R})$  admits an orthogonal scale detail subspaces decomposition

$$(2.3) \quad \mathcal{L}^2(\mathbb{R}) = \bigoplus_{m \in \mathbb{Z}} \mathcal{W}_m(\psi).$$

Moreover, since  $D$  has a bounded inverse, we also have

$$(2.4) \quad \mathcal{L}^2(\mathbb{R}) = \bigoplus_{m \in \mathbb{Z}} D^m \mathcal{W}_0(\psi),$$

where

$$(2.5) \quad \mathcal{W}_0(\psi) := \bigvee_{n \in \mathbb{Z}} \psi((\cdot) - n),$$

is a generating — because of (2.4) — and  $D$ -wandering subspace — because

$$(2.6) \quad D^m \mathcal{W}_0(\psi) \perp D^{m'} \mathcal{W}_0(\psi), \quad \text{whenever } m \neq m'.$$

What is interesting is the fact that (2.4) actually defines  $D$  as a bilateral shift whose multiplicity is the dimension of its generating wandering subspace  $\mathcal{W}_0(\psi)$  [3]. This fact will be used in Section 3.

Now, if a wavelet  $\psi(\cdot)$  is “derived” from a scaling function  $\phi(\cdot)$  — generating a MRA  $\{\mathcal{V}_m\}_{m \in \mathbb{Z}}$  — that is, the subspaces  $\mathcal{V}_m$  — called scaling approximation subspaces — satisfy the following properties [9, 10, 11]:

- (o)  $\mathcal{V}_0 := \bigvee_{n \in \mathbb{Z}} \phi((\cdot) - n)$  and  $\mathcal{V}_{m+1} = D\mathcal{V}_m$ ,  $(m, n) \in \mathbb{Z}^2$ ,
- (i)  $\mathcal{V}_m \subset \mathcal{V}_{m+1}$ ,  $m \in \mathbb{Z}$ ,
- (ii)  $\bigcap_{m \in \mathbb{Z}} \mathcal{V}_m = \{0\}$ ,
- (iii)  $\bigcup_{m \in \mathbb{Z}} \mathcal{V}_m = \mathcal{L}^2(\mathbb{R})$ .

Then we also have

$$(2.7) \quad \mathcal{V}_{m+1} = \mathcal{V}_m \oplus \mathcal{W}_m(\psi), \quad m \in \mathbb{Z}.$$

This establishes relationship between the scaling function  $\phi(\cdot)$  and the associated wavelet  $\psi(\cdot)$ . Note that in property (o), the functions  $\phi((\cdot) - n)$ ,  $n \in \mathbb{Z}$ , are taken to be orthonormal.

The place where DiEq were born is in the “nested” property (i).

It follows from property (o) that

$$(2.8) \quad \mathcal{V}_m := \bigvee_{n \in \mathbb{Z}} D^m \phi((\cdot) - n), \quad m \in \mathbb{Z}.$$

Moreover, each  $\mathcal{V}_m$  can also be “represented” in terms of the scale detail subspaces  $\mathcal{W}_{m'}(\psi)$ ,  $-\infty < m' \leq m - 1$ , as

$$(2.9) \quad \mathcal{V}_m = \bigoplus_{m'=-\infty}^{m-1} \mathcal{W}_{m'}(\psi), \quad m \in \mathbb{Z}.$$

This is a consequence of (2.7).

To distinguish between  $\mathcal{V}_m$  in (2.8) and its representation in (2.9) we denote the right hand side of (2.9) by  $\mathcal{V}_m(\psi)$

$$(2.10) \quad \mathcal{V}_m(\psi) := \bigoplus_{m'=-\infty}^{m-1} \mathcal{W}_{m'}(\psi), \quad m \in \mathbb{Z},$$

to indicate that, since it depends on the wavelet functions  $\psi_{m,n}(\cdot)$ , it depends on the wavelet  $\psi(\cdot)$  as well. Moreover,  $\mathcal{V}_m(\psi)$ ,  $m \in \mathbb{Z}$ , automatically satisfy the MRA properties (i), (ii) and (iii).

It is evident that dyadic-scaling plays a central role while time-shifting is somewhat neglected! In other words, Wavelets and MRA are basically “scale-based” theories.

An important fact which we feel has been “overlooked” is the fact that one can also construct “time-shift detail subspaces”  $\mathcal{H}_n(\psi)$ ,  $n \in \mathbb{Z}$ , from the wavelet functions  $\psi_{m,n}(\cdot)$ ,  $(m, n) \in \mathbb{Z}^2$ , as [6],

$$(2.11) \quad \mathcal{H}_n(\psi) := \bigvee_{m \in \mathbb{Z}} D^m \psi((\cdot) - n), \quad n \in \mathbb{Z}.$$

Moreover, these  $\mathcal{H}_n(\psi)$  are also orthogonal and form a second o.s.b. for  $\mathcal{L}^2(\mathbb{R})$ . Consequently, we now have, in addition to (2.3), the time-shift orthogonal decomposition

$$(2.12) \quad \mathcal{L}^2(\mathbb{R}) = \bigoplus_{n \in \mathbb{Z}} \mathcal{H}_n(\psi).$$

This suggests that one ought to explore “time-shift-based” approach to Wavelets and MRA. Preliminary results along these lines were reported in [7, 8].

To derive the proposed TiEq we begin with the time-shift detail subspaces  $\mathcal{G}_n(\psi)$  defined by

$$(2.13) \quad \mathcal{G}_n(\psi) := \bigoplus_{n'=-\infty}^{n-1} \mathcal{H}_{n'}(\psi), \quad n \in \mathbb{Z}.$$

These are simply a time-shift analog of the scale subspaces  $\mathcal{V}_m(\psi)$ . Moreover, it is a simple matter to verify that  $\{\mathcal{G}_n(\psi)\}$  also satisfies the MRA properties (i), (ii) and (iii).

The difference between  $\{\mathcal{V}_m(\psi)\}_{m \in \mathbb{Z}}$  and  $\{\mathcal{G}_n(\psi)\}_{n \in \mathbb{Z}}$  is that the former consists of scale detail subspaces and it represents the original MRA  $\{\mathcal{V}_m\}_{m \in \mathbb{Z}}$ , while the latter consists of time-shift detail subspaces, hence it cannot represent the scaling subspaces  $\{\mathcal{V}_m\}_{m \in \mathbb{Z}}$ . This is also due in part to the fact that  $\mathcal{G}_n(\psi)$  is  $D$ -reducing while  $\mathcal{V}_m$  is only  $D^*$ -invariant.

Suppose now that there is a function  $\varphi(\cdot) \in \mathcal{L}^2(\mathbb{R})$  such that

$$(2.14) \quad \varphi((\cdot) - n) \perp D^m \varphi((\cdot) - n), \quad \forall (m, n) \in \mathbb{Z}^2.$$

Let the subspaces  $\mathcal{T}_n$ ,  $n \in \mathbb{Z}$ , be defined by

$$(2.15) \quad \mathcal{T}_n := \bigvee_m D^m \varphi((\cdot) - n), \quad n \in \mathbb{Z},$$

and satisfy the following properties:

- (i)  $\mathcal{T}_n \subset \mathcal{T}_{n+1}$ ,  $n \in \mathbb{Z}$ ,
- (ii)  $\bigcap_{n \in \mathbb{Z}} \mathcal{T}_n = \{0\}$ ,
- (iii)  $\bigcup_{m \in \mathbb{Z}} \mathcal{T}_m = \mathcal{L}^2(\mathbb{R})$ .

Moreover,

$$(2.16) \quad \mathcal{T}_{n+1} = \mathcal{T}_n \oplus \mathcal{H}_n(\psi), \quad n \in \mathbb{Z},$$

where  $\mathcal{H}_n(\psi)$  is as previously defined. Then clearly  $\mathcal{T}_n$  also admits the representation

$$(2.17) \quad \mathcal{T}_n = \bigoplus_{n'=-\infty}^{n-1} \mathcal{H}_{n'}(\psi) := \mathcal{G}_n(\psi), \quad n \in \mathbb{Z}.$$

We note that  $\mathcal{T}_n$  as defined by (2.15) is  $D$ -reducing and so is  $\mathcal{G}_n(\psi)$ .

It follows from (2.15) and property (i) that

$$(2.18) \quad \mathcal{T}_0 := \bigvee_{m \in \mathbb{Z}} D^m \varphi(\cdot) \subset \mathcal{T}_1 := \bigvee_{m \in \mathbb{Z}} D^m \varphi((\cdot) - 1).$$

Therefore, since  $\varphi(\cdot)$  also lives in  $\mathcal{T}_1$  it can be represented in terms of the orthonormal functions  $D^m \varphi((\cdot) - 1)$ ,  $m \in \mathbb{Z}$  — spanning  $\mathcal{T}_1$  — as

$$(2.19) \quad \varphi(\cdot) = \sum_{m \in \mathbb{Z}} \beta_m D^m \varphi((\cdot) - 1).$$

This is the basic Time-Shift Equation announced in (1.4). We also have, as in the case of the DiEq (1.1),

$$(2.20) \quad \int_{-\infty}^{\infty} \varphi(t) dt = 1 \quad \implies \quad \sum_{m \in \mathbb{Z}} \frac{\beta_m}{\sqrt{2^m}} = 1.$$

In general we have the TiEq

$$(2.21) \quad \varphi((\cdot) - n) = \sum_{m \in \mathbb{Z}} \beta_{m,n} D^m \varphi((\cdot) - (n+1)), \quad n \in \mathbb{Z}.$$

### 3. A CONNECTION BETWEEN TIEQ AND DIEQ

We close by showing that a TiEq can be converted — up to a unitary operator — into a DiEq and vice versa.

First, given a wavelet  $\psi(\cdot) \in \mathcal{L}^2(\mathbb{R})$ , then the space  $\mathcal{L}^2(\mathbb{R})$  automatically admits the scale detail subspaces orthogonal decomposition (2.4)

$$(3.1) \quad \mathcal{L}^2(\mathbb{R}) = \bigoplus_{m \in \mathbb{Z}} \mathcal{W}_m(\psi) = \bigoplus_{m \in \mathbb{Z}} D^m \mathcal{W}_0(\psi) := \mathcal{L}^2(\mathbb{R}; D),$$

where  $\mathcal{W}_0(\psi)$  defined by (2.5)

$$\mathcal{W}_0(\psi) := \bigvee_{n \in \mathbb{Z}} \psi((\cdot) - n),$$

is a  $D$ -wandering generating subspace, and  $\mathcal{L}^2(\mathbb{R}; D)$  indicates that (3.1) is a  $D$ -wandering subspaces representation of  $\mathcal{L}^2(\mathbb{R})$ .

For the unit time-shift operator  $T$ , unfortunately, there is no decomposition in terms of the wavelet functions  $\psi_{m,n}(\cdot)$  — similar to (3.1). However, since  $T$  is also a bilateral shift of countably infinite multiplicity, the space  $\mathcal{L}^2(\mathbb{R})$  can admit a  $T$ -wandering subspaces orthogonal representation of the form

$$(3.2) \quad \mathcal{L}^2(\mathbb{R}) = \bigoplus_{n \in \mathbb{Z}} T^n \mathcal{W}_{0,T} := \mathcal{L}^2(\mathbb{R}; T),$$

where  $\mathcal{W}_{0,T}$  is a  $T$ -wandering generating subspace.

It is well known that bilateral shifts of equal multiplicity are unitarily equivalent [13, Chapter 1]. This for the case of the bilateral shifts  $D$  and  $T$  can be seen as follows.

Next, let  $f(\cdot) \in \mathcal{L}^2(\mathbb{R}; D)$  so we have the dyadic-scale orthogonal representation

$$(3.3) \quad f(\cdot) = \sum_{m \in \mathbb{Z}} D^m w_m(\cdot), \quad w_m(\cdot) \in \mathcal{W}_0(\psi), \quad m \in \mathbb{Z}, \quad \text{and} \quad \sum_{m \in \mathbb{Z}} \|w_m(\cdot)\|^2 = \|f(\cdot)\|^2.$$

Let

$$\omega: \mathcal{W}_0(\psi) \rightarrow \mathcal{W}_{0,T}$$

be a unitary operator sending  $\mathcal{W}_0(\psi)$  onto  $\mathcal{W}_{0,T}$ . Then the operator

$$\Omega: \mathcal{L}^2(\mathbb{R}; D) \rightarrow \mathcal{L}^2(\mathbb{R}, T),$$

defined by

$$(3.4) \quad \Omega f(\cdot) := \sum_{m \in \mathbb{Z}} T^m \omega w_m(\cdot),$$

is clearly unitary. Moreover, it is easy to see that

$$(3.5) \quad \Omega D = T \Omega,$$

that is,  $D$  and  $T$  are unitarily equivalent (both are bilateral shifts of the same cardinality).

We summarize the above in the next proposition.

**Proposition 1.** *Let  $\psi(\cdot) \in \mathcal{L}^2(\mathbb{R})$  be a wavelet then the space  $\mathcal{L}^2(\mathbb{R})$  admits a dyadic-scaling representation  $\mathcal{L}^2(\mathbb{R}; D)$  defined by the orthogonal decomposition (3.1), as well as a unit-time-shift representation  $\mathcal{L}^2(\mathbb{R}; T)$  defined by (3.3). The former is unique while the latter needs not be.*

Now, return to the basic TiEq (1.4)

$$(3.6) \quad \varphi(\cdot) = \sum_{m \in \mathbb{Z}} \beta_m D^m \varphi((\cdot) - 1) = \sum_{m \in \mathbb{Z}} \beta_m D^m T \varphi(\cdot),$$

which can be rewritten as

$$(3.7) \quad D^* \varphi(\cdot) = \sum_{m \in \mathbb{Z}} \beta_m D^{m-1} \varphi((\cdot) - 1).$$

Substituting for  $D$  from (3.5) we obtain

$$(3.8) \quad D^* \varphi(\cdot) = \sum_{n \in \mathbb{Z}} \beta_n \Omega^* T^{n-1} \Omega \varphi((\cdot) - 1),$$

where, since the right hand side is summing with respect to time-shifts, we have replaced  $m$  by  $n$ . Then, since  $\Omega^*$  is also unitary, we can have

$$(3.9) \quad \Omega D^* \varphi(\cdot) = \sum_{n \in \mathbb{Z}} \beta_n T^{n-1} \Omega \varphi((\cdot) - 1).$$

This is clearly a Dilation-Type Equation. To see this, let us rewrite the basic DiEq (1.1) as

$$(3.10) \quad D^* \phi(\cdot) = \sum_{n \in \mathbb{Z}} c_n T^{n-1} \phi((\cdot) - 1),$$

which is simply equation (3.9) for  $\Omega = I$ , and in which  $\varphi(\cdot)$  as well as  $\beta_n$  are replaced by  $\phi(\cdot)$  and  $c_n$ . We have therefore shown that a TiEq of the form (3.8) is connected to a DiEq of the form (3.9) via the ‘‘Dilation-Type Equation’’ (3.10). In exactly the same way, a DiEq of the form (3.10) is connected to a TiEq of the form (3.7) via the ‘‘Time-Shift-Type Equation’’

$$(3.11) \quad \Omega^* D^* \phi(\cdot) = \sum_{n \in \mathbb{Z}} c_n D^{n-1} \Omega^* \phi((\cdot) - 1).$$

This note is intended as a brief introduction to TiEq. Further work on these equations as well as on Time-Shift MRA will be reported elsewhere.

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